



TECHNOLOGY DRIVEN. WARFIGHTER FOCUSED.

Michael Blain – Deputy Associate Director Ground Vehicle Power and Mobility 27 July 2011

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Report Documentation Page

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Selecting the Right Technologies to Meet the Challenges



Power Demand Primary



Electrical Powe



Vehicle Agility Requirements



Consumption Fuel



Increasing demands, operational flexibility, and inter-relationships Requires a Systems Engineering approach and investments in key technology areas



Propulsion & Thermal Management



Non-Prime Power Systems



Advanced **Propulsion**



Track & Suspension

Systems Level Analysis, Integration and Testing



GVPM Technology Taxonomy



rmal Managem Propulsion and



Diesel **Engines**

Turbine



Transmissions

Advanced **Radiators**



Electrified

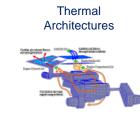
Thermal

Components

Advanced Electronics Cooling



Heat Recovery



Systems on-Prime



JP-8

Fuel Cell APU

Rotary Engine **APU**



Advanced Lithium Ion Batteries





Capacitors



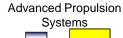
Li-Ion / Ultracap Hybrid **Energy Storage**

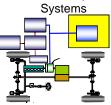
Advanced Propulsion



Integrated Starter Generator

Track









Advanced Propulsion Reliability Testing

High Temperature / Power SiC Power **Electronics**





Wide Band Gap Materials (SiC)

Track and



Suspension **Systems**











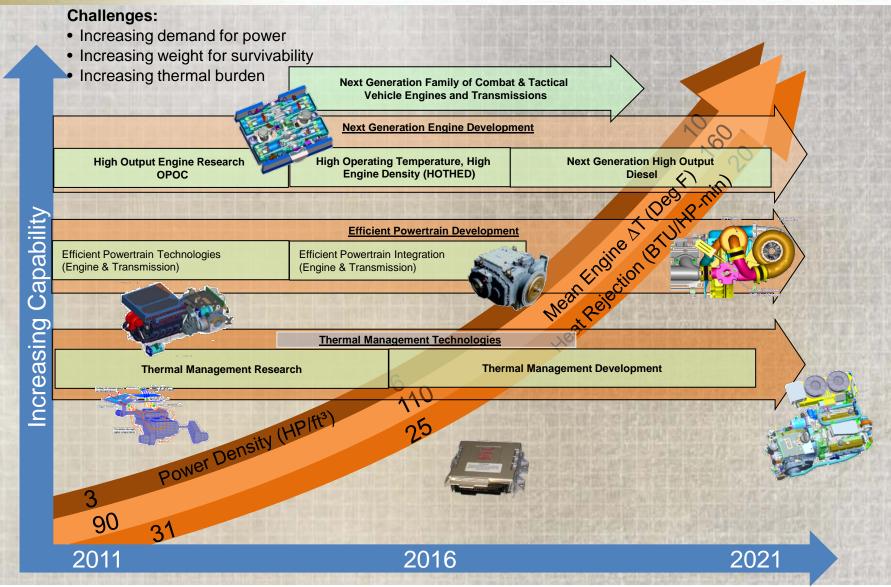


Track Elastomer Research



RDECOM Propulsion and Thermal Systems Thrust Area



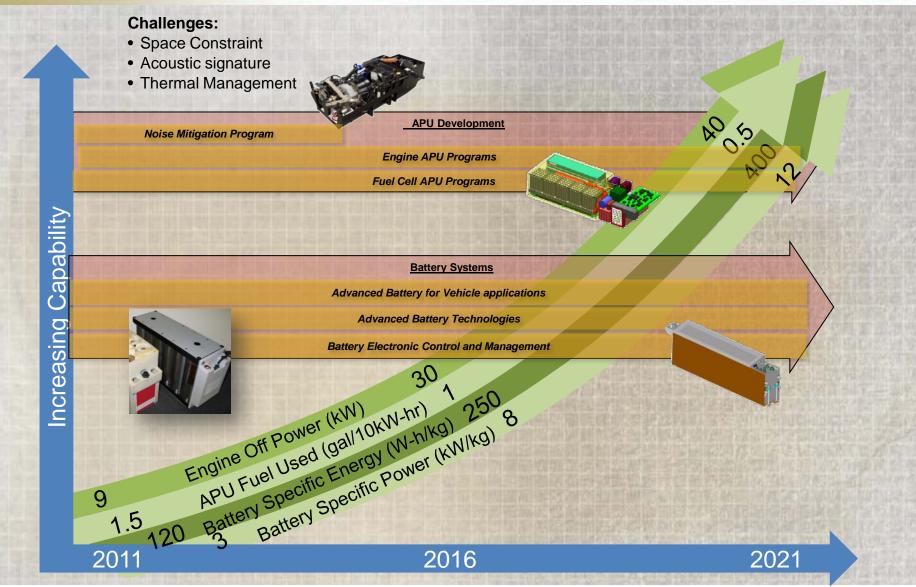


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Non-Primary Power Thrust Area



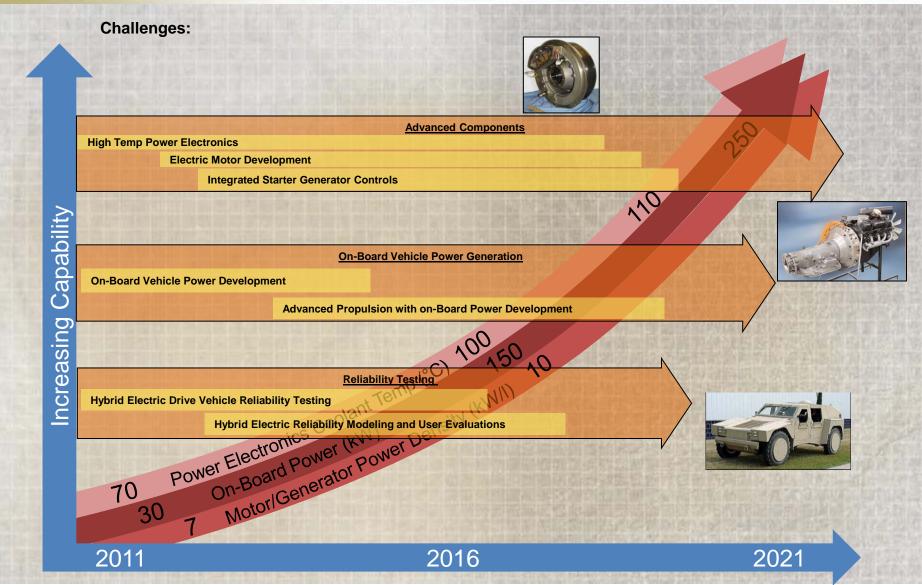


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Advanced Propulsion Thrust Area

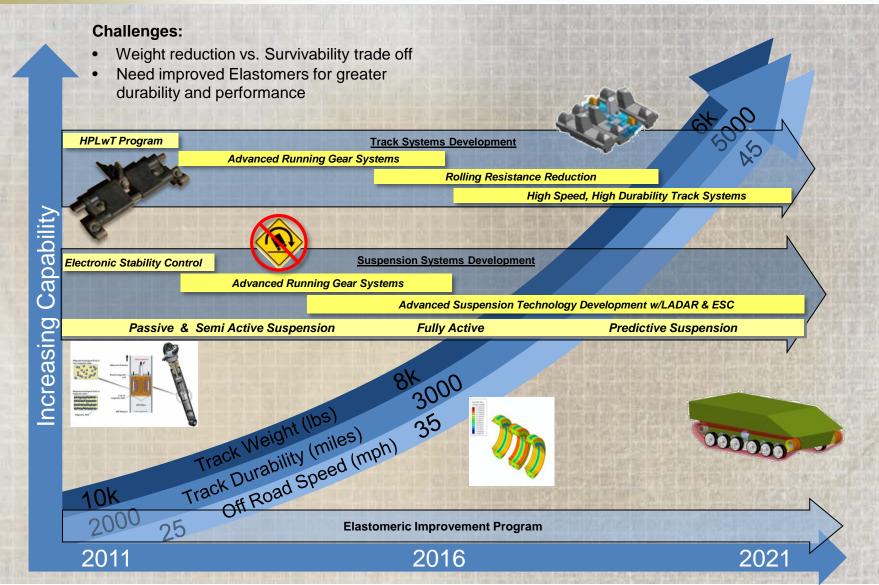






Track and Suspension Thrust Area

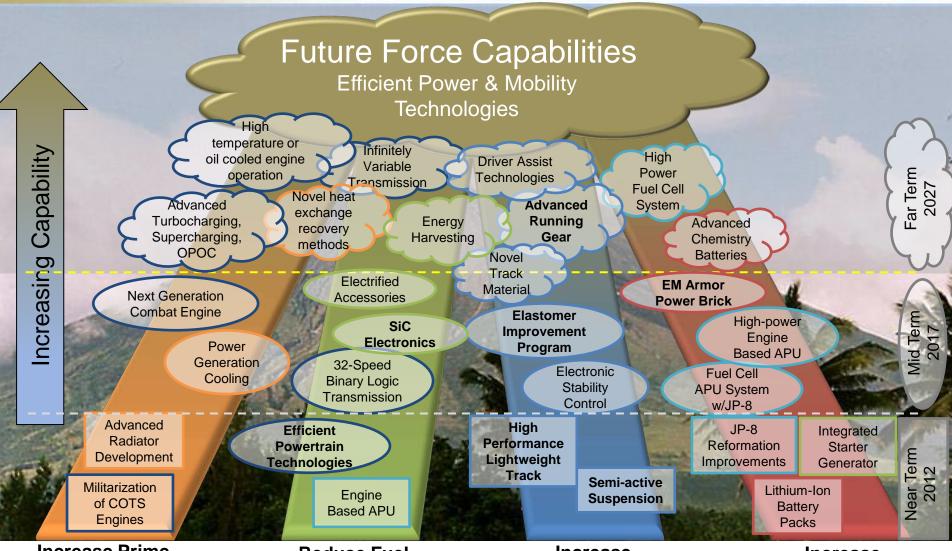






Capability Based Technology Strategy





Increase Prime Power

Reduce Fuel Consumption

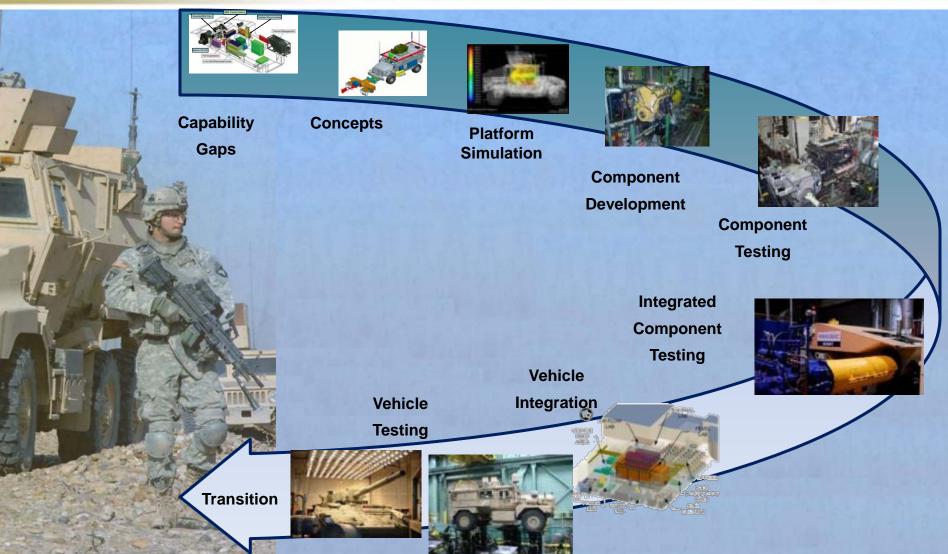
Increase **Vehicle Agility**

Increase **Electrical Power** TECHNOLOGY DRIVEN. WARFIGHTER FOCUSED.



Laboratory Support Throughout the Ground Platform Lifecycle





Enabling Warfighter Capability Through Technology Development & Integration

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It's all about...Supporting the Warfighter





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Back Up Charts



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Track Systems





T-154



T-158LL



T-157i T-161



T-150



T-107 / T-160

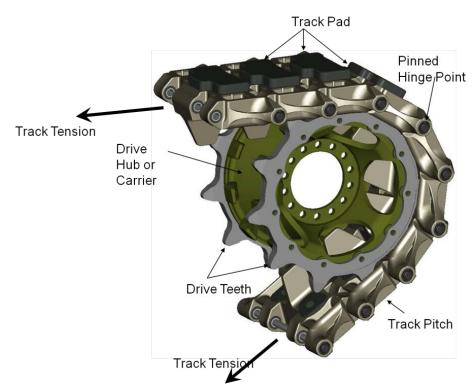


Background: Track Purpose & Anatomy

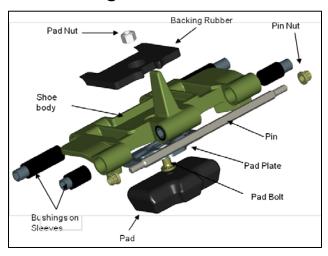


Purpose of a Track System

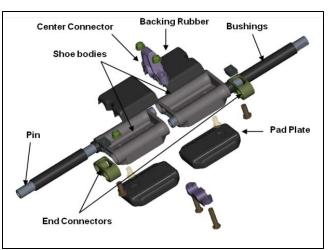
- Provides a transportable continuous, smooth road surface
- Supports vehicle load across large soft surfaces
- Enable large obstacle/gap crossing capability



Single Pin Track



Double Pin Track





Current Configurations



Class	Vehicle		Track	Max GVW (ton)	Weight (lb/ft)	Width (in)	Durability (Mi)
Light	M113		T-130 (Replace by T150)	15	40	15	3000
			T-150	15	45	15	10000
Medium	Bradley		T-157i (Replace by T161)	32	68	21	2500
			T-161	40	67	19.2	6000
	Paladin		T-154	32	62	15	5000
	PIM AMPV		T-161	40	67	19.2	6000
Heavy	M1	The state of the s	T-158LL	75	107	25	2100
	GCV						
	M88		T-107	75	102	28	1200
			XT-160 (In Qualification)	75 .Aggiried	132	28	4000 14



Track System Commonality Options



Class	Vehicle	Track	Max GVW (ton)	Weight (lb/ft)	Width (in)	Durability (Mi)
Medium	Bradley	T-161	40	67	19.2	6000
	Paladin*					
	PIM					
	AMPV					
Heavy	M1		75	107	25	2100
	GCV	T-158LL				
	M88	XT-160	75	132	28	4000

Three Track Systems Support Seven Vehicle Platforms

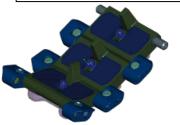
^{*} Issues exist with increased track width



PM HBCT Track Systems



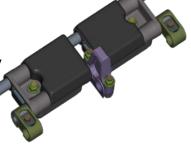
T150 Double Pin



M113 fov 15.0" Wide 43.4 lbs/ft 15-22 ton fov 10,000 miles

T158LL Double Pin

Abrams
25.0" Wide
110 lbs/ft
56-75 ton fov
2100 miles



T107 Double Pin



T130 Single Pin

M113 fov 15.0" Wide 41.5 lbs/ft 15-22 ton fov 3000 miles



Paladin 15.0" Wide

58 lbs/ft 25-30 ton fov 5000 miles

> Bradley fov 21.0" Wide 71.0 lbs/ft 25-35 ton fov 2400 miles

T157i Single Pin

16



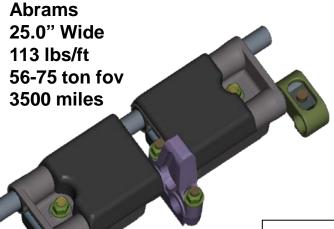
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PM HBCT Development Track Systems



XT158IR Double Pin



T160 Double Pin

M88 fov 28.0" Wide 135 lbs/ft 56-75 ton fov 3500 miles

